Overview of Assembly Language

Chapter 3

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Outline

- Assembly language statements
- Data allocation
- Where are the operands?
 - * Addressing modes
 - » Register
 - » Immediate
 - » Direct
 - » Indirect
- Data transfer instructions
 - * mov, xchg, and xlat
 - * PTR directive

- Overview of assembly language instructions
 - * Arithmetic
 - * Conditional
 - * Logical
 - * Shift
 - * Rotate
- Defining constants
 - * EQU and = directives
- Illustrative examples
- Performance: When to use the xlat instruction

Assembly Language Statements

Three different classes

- * Instructions
 - » Tell CPU what to do
 - » Executable instructions with an op-code
- * Directives (or pseudo-ops)
 - » Provide information to assembler on various aspects of the assembly process
 - » Non-executable
 - Do not generate machine language instructions

* Macros

- » A shorthand notation for a group of statements
- » A sophisticated text substitution mechanism with parameters

Assembly Language Statements (cont'd)

Assembly language statement format:

[label] mnemonic [operands] [;comment]

- * Typically one statement per line
- * Fields in [] are optional
- * label serves two distinct purposes:
 - » To label an instruction
 - Can transfer program execution to the labeled instruction
 - » To label an identifier or constant
- * mnemonic identifies the operation (e.g. add, or)
- * operands specify the data required by the operation
 - » Executable instructions can have zero to three operands

Assembly Language Statements (cont'd)

* comments

» Begin with a semicolon (;) and extend to the end of the line

Examples

```
repeat: inc result ; increment result

CR EQU ODH ; carriage return character
```

White space can be used to improve readability
 repeat:

```
inc result; increment result
```

Data Allocation

Variable declaration in a high-level language such as C

```
char response
int value
float total
double average_value
```

specifies

- » Amount storage required (1 byte, 2 bytes, ...)
- » Label to identify the storage allocated (response, value, ...)
- » Interpretation of the bits stored (signed, floating point, ...)
 - Bit pattern **1000 1101 1011 1001** is interpreted as
 - \rightarrow -29,255 as a signed number
 - → 36,281 as an unsigned number

- In assembly language, we use the *define* directive
 - * Define directive can be used
 - » To reserve storage space
 - » To label the storage space
 - » To initialize
 - » But *no interpretation* is attached to the bits stored
 - Interpretation is up to the program code
 - * Define directive goes into the .DATA part of the assembly language program
- Define directive format

[var-name] D? init-value [,init-value],...

• Five define directives

```
DB Define Byte ;allocates 1 byte
DW Define Word ;allocates 2 bytes
DD Define Doubleword ;allocates 4 bytes
DQ Define Quadword ;allocates 8 bytes
DT Define Ten bytes ;allocates 10 bytes
```

Examples

```
sorted DB 'y'
response DB ? ;no initialization
value DW 25159
float1 DO 1.234
```

Multiple definitions can be abbreviated

Example

```
message DB 'B'
DB 'y'
DB 'e'
DB ODH
DB OAH
```

can be written as

message DB 'B', 'y', 'e', ODH, OAH

More compactly as

message DB 'Bye', ODH, OAH

• Multiple definitions can be cumbersome to initialize data structures such as arrays

Example

To declare and initialize an integer array of 8 elements marks DW 0,0,0,0,0,0,0

- What if we want to declare and initialize to zero an array of 200 elements?
 - * There is a better way of doing this than repeating zero 200 times in the above statement
 - » Assembler provides a directive to do this (DUP directive)

- Multiple initializations
 - * The DUP assembler directive allows multiple initializations to the same value
 - * Previous marks array can be compactly declared as

```
marks DW 8 DUP (0)
```

Examples

The DUP directive may also be nested

Example

```
stars DB 4 DUP(3 DUP ('*'),2 DUP ('?'),5 DUP ('!'))

Reserves 40-bytes space and initializes it as

***??!!!!!***??!!!!!!
```

Example

```
matrix DW 10 DUP (5 DUP (0))
```

defines a 10X5 matrix and initializes its elements to zero

This declaration can also be done by

matrix DW 50 DUP (0)

Symbol Table

* Assembler builds a symbol table so we can refer to the allocated storage space by the associated label

Example

.DATA			name	offset
value	DW	0	value	0
sum	DD	0	sum	2
marks	DW	10 DUP (?)	marks	6
message	DB	`The grade is:',0	message	26
char1	DB	?	char1	40

Correspondence to C Data Types

Directive	C data type
DB	char
DW	int, unsigned
DD	float, long
DQ	double
DT	internal intermediate float value

LABEL Directive

- * LABEL directive provides another way to name a memory location
- * Format:

name	LABEL	type
type can be		
BYTE	1 byte	
WORD	2 bytes	}
DWORD	4 bytes	}
QWORD	8 bytes	}
TWORD	10 byte	s

LABEL Directive

Example

```
count LABEL WORD
Lo-count DB 0
Hi_count DB 0
.CODE
...
mov Lo_count,AL
mov Hi_count,CL

* count refers to the 16-bit value

* Lo_count refers to the low byte
```

* **Hi_count** refers to the high byte

Where Are the Operands?

- Operands required by an operation can be specified in a variety of ways
- A few basic ways are:
 - * operand in a register
 - register addressing mode
 - * operand in the instruction itself
 - immediate addressing mode
 - * operand in memory
 - variety of addressing modes
 - → direct and indirect addressing modes
 - * operand at an I/O port

Register addressing mode

- * Most efficient way of specifying an operand
 - » operand is in an internal register

Examples

mov EAX, EBX

mov BX,CX

* The **mov** instruction

mov destination, source copies data from source to destination

Immediate addressing mode

- * Data is part of the instruction
 - » operand is located in the code segment along with the instruction
 - » Efficient as no separate operand fetch is needed
 - » Typically used to specify a constant

Example

mov AL,75

* This instruction uses register addressing mode for specifying the *destination* and immediate addressing mode to specify the *source*

Direct addressing mode

- * Data is in the data segment
 - » Need a logical address to access data
 - Two components: segment:offset
 - » Various addressing modes to specify the offset component
 - offset part is referred to as the *effective address*
- * The offset is specified directly as part of the instruction
- * We write assembly language programs using memory labels (e.g., declared using DB, DW, LABEL,...)
 - » Assembler computes the offset value for the label
 - Uses symbol table to compute the offset of a label

Direct addressing mode

Examples

mov AL, response

» Assembler replaces **response** by its effective address (i.e., its offset value from the symbol table)

mov table1,56

» table1 is declared as

- » Since the assembler replaces table1 by its effective address, this instruction refers to the first element of table1
 - In C, it is equivalent to

$$table1[0] = 56$$

Direct addressing mode

- Problem with direct addressing
 - * Useful only to specify simple variables
 - Causes serious problems in addressing data types such as arrays
 - » As an example, consider adding elements of an array
 - Direct addressing does not facilitate using a loop structure to iterate through the array
 - We have to write an instruction to add each element of the array
- Indirect addressing mode remedies this problem

Indirect addressing mode

- The offset is specified indirectly via a register
 - * Sometimes called *register indirect* addressing mode
 - * For 16-bit addressing, the offset value can be in one of the three registers: BX, SI, or DI
 - * For 32-bit addressing, all 32-bit registers can be used

Example

mov AX, [BX]

- * Square brackets [] are used to indicate that BX is holding an offset value
 - » BX contains a pointer to the operand, not the operand itself

 Using indirect addressing mode, we can process arrays using loops

Example: Summing array elements

- * Load the starting address (i.e., offset) of the array into BX
- * Loop for each element in the array
 - » Get the value using the offset in BX
 - Use indirect addressing
 - » Add the value to the running total
 - » Update the offset in BX to point to the next element of the array

Loading offset value into a register

- Suppose we want to load BX with the offset value of table1
- We cannot write

mov BX, table1

- Two ways of loading offset value
 - » Using OFFSET assembler directive
 - Executed only at the assembly time
 - » Using lea instruction
 - This is a processor instruction
 - Executed at run time

Loading offset value into a register

- Using OFFSET assembler directive
 - * The previous example can be written as

mov BX,OFFSET table1

- Using lea (load effective address) instruction
 - * The format of **lea** instruction is

lea register, source

* The previous example can be written as

lea BX, table1

Loading offset value into a register

Which one to use -- OFFSET or **lea**?

- * Use OFFSET if possible
 - » OFFSET incurs only one-time overhead (at assembly time)
 - » **lea** incurs run time overhead (every time you run the program)
- * May have to use **lea** in some instances
 - » When the needed data is available at run time only
 - An index passed as a parameter to a procedure
 - » We can write

lea BX,table1[SI]

to load BX with the address of an element of **table1** whose index is in SI register

» We cannot use the OFFSET directive in this case

Data Transfer Instructions

- We will look at three instructions
 - * mov (move)
 - » Actually copy
 - * xchg (exchange)
 - » Exchanges two operands
 - * **xlat** (translate)
 - » Translates byte values using a translation table
- Other data transfer instructions such as
 - * movsx (move sign extended)
 - * movzx (move zero extended)

are discussed in Chapter 6

The mov instruction

* The format is

mov destination, source

- » Copies the value from **source** to **destination**
- **source** is not altered as a result of copying
- » Both operands should be of same size
- >> source and destination cannot both be in memory
 - Most Pentium instructions do not allow both operands to be located in memory
 - Pentium provides special instructions to facilitate memory-to-memory block copying of data

The mov instruction

* Five types of operand combinations are allowed:

Instruction type		Example	
mov	register, register	mov	DX,CX
mov	register,immediate	mov	BL,100
mov	register, memory	mov	BX,count
mov	memory, register	mov	count,SI
mov	memory, immediate	mov	count,23

* The operand combinations are valid for all instructions that require two operands

Ambiguous moves: PTR directive

For the following data definitions

.DATA

```
table1 DW 20 DUP (0) status DB 7 DUP (1)
```

the last two **mov** instructions are ambiguous

```
mov BX,OFFSET table1
mov SI,OFFSET status
mov [BX],100
mov [SI],100
```

* Not clear whether the assembler should use byte or word equivalent of 100

Ambiguous moves: PTR directive

- The PTR assembler directive can be used to clarify
- The last two **mov** instructions can be written as

```
mov WORD PTR [BX],100 mov BYTE PTR [SI],100
```

- * WORD and BYTE are called *type specifiers*
- We can also use the following type specifiers:

```
DWORD for doubleword values
```

QWORD for quadword values

TWORD for ten byte values

The xchg instruction

• The syntax is

xchg operand1, operand2

Exchanges the values of operand1 and operand2

Examples

xchg EAX, EDX

xchg response, CL

xchg total,DX

• Without the **xchg** instruction, we need a temporary register to exchange values using only the **mov** instruction

The xchg instruction

• The **xchg** instruction is useful for conversion of 16-bit data between little endian and big endian forms

* Example:

mov AL, AH

converts the data in AX into the other endian form

• Pentium provides **bswap** instruction to do similar conversion on 32-bit data

bswap 32-bit register

* bswap works only on data located in a 32-bit register

The xlat instruction

- The **xlat** instruction translates bytes
- The format is
- To use xlat instruction
 - » BX should be loaded with the starting address of the translation table
 - » AL must contain an index in to the table
 - Index value starts at zero
 - » The instruction reads the byte at this index in the translation table and stores this value in AL
 - The index value in AL is lost
 - » Translation table can have at most 256 entries (due to AL)

The xlat instruction

Example: Encrypting digits

```
Input digits: 0 1 2 3 4 5 6 7 8 9
   Encrypted digits: 4 6 9 5 0 3 1 8 7 2
.DATA
xlat_table DB '4695031872'
...
.CODE
mov BX,OFFSET xlat_table
GetCh AL
sub AL,'0'; converts input character to index xlatb ; AL = encrypted digit character
PutCh AL
```

Overview of Assembly Instructions

- Pentium provides several types of instructions
- Brief overview of some basic instructions:
 - * Arithmetic instructions
 - * Jump instructions
 - * Loop instruction
 - * Logical instructions
 - * Shift instructions
 - * Rotate instructions
- These sample instructions allows you to write reasonable assembly language programs

Arithmetic Instructions

INC and DEC instructions

* Format:

inc destination

dec destination

* Semantics:

```
destination := destination +/- 1
```

» **destination** can be 8-, 16-, or 32-bit operand, in memory or register

→ No immediate operand

Examples

```
inc BX ; BX := BX+1
```

dec value ; value := value-1

Arithmetic Instructions

ADD instruction

* Format:

add destination, source

* Semantics:

destination := (destination)+(source)

Examples

add EBX, EAX

add value, 35

- * inc EAX is better than add EAX,1
 - inc takes less space
 - Both execute at about the same speed

Arithmetic Instructions

SUB instruction

* Format:

sub destination, source

* Semantics:

destination := (destination)-(source)

Examples

sub EBX, EAX

sub value, 35

- * dec EAX is better than sub EAX,1
 - dec takes less space
 - Both execute at about the same speed

Arithmetic Instructions

CMP instruction

* Format:

cmp destination, source

* Semantics:

(destination)-(source)

- * destination and source are not altered
- * Useful to test relationship (>, =) between two operands
- * Used in conjunction with conditional jump instructions for decision making purposes

Examples

cmp EBX, EAX

cmp count, 100

Jump Instructions

<u>Unconditional Jump</u>

* Format:

```
jmp label
```

- * Semantics:
 - » Execution is transferred to the instruction identified by **label**
- Examples: Infinite loop

Jump Instructions

Conditional Jump

* Format:

```
j<cond> label
```

- * Semantics:
 - » Execution is transferred to the instruction identified by label only if <cond> is met
- Examples: Testing for carriage return

```
GetCh AL

cmp AL,0DH; 0DH = ASCII carriage return

je CR_received

inc CL

CR received:
```

Jump Instructions

Conditional Jump

- * Some conditional jump instructions
 - Treats operands of the CMP instruction as signed numbers

```
je jump if equal
jg jump if greater
jl jump if less
jge jump if greater or equal
jle jump if less or equal
jne jump if not equal
```

Jump Instructions

Conditional Jump

* Conditional jump instructions can also test values of the individual flags

```
jz jump if zero (i.e., if ZF = 1)

jnz jump if not zero (i.e., if ZF = 0)

jc jump if carry (i.e., if CF = 1)

jnc jump if not carry (i.e., if CF = 0)
```

- * jz is synonymous for je
- * jnz is synonymous for jne

Loop Instruction

LOOP Instruction

* Format:

loop target

- * Semantics:
 - » Decrements CX and jumps to target if $CX \neq 0$
 - CX should be loaded with a loop count value
- Example: Executes loop body 50 times

```
mov CX,50
```

repeat:

<loop body>

loop repeat

. . .

Loop Instruction

• The previous example is equivalent to

Logical Instructions

* Format:

```
and destination, source
```

or destination, source

not destination

- * Semantics:
 - » Performs the standard bitwise logical operations
 - result goes to destination
- * TEST is a non-destructive AND instruction test destination, source
- * Performs logical AND but the result is not stored in **destination** (like the CMP instruction)

Logical Instructions

Example: Testing the value in AL for odd/even number

Shift Instructions

* Format:

Shift left

shl destination, count

shl destination,CL

Shift right

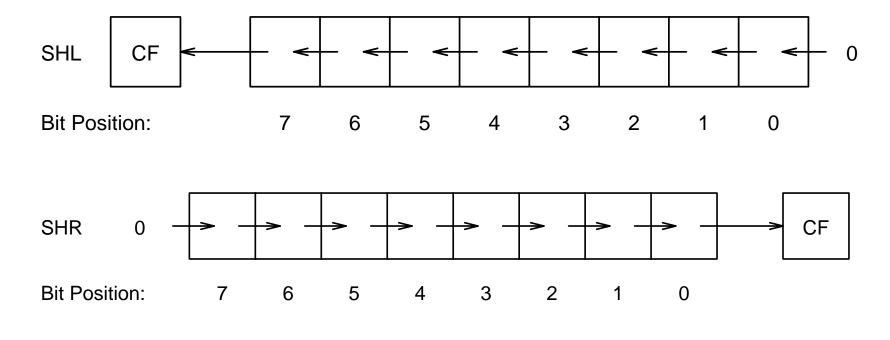
shr destination, count

shr destination, CL

- * Semantics:
 - » Performs left/right shift of destination by the value in count or CL register
 - **CL** register contents are not altered

Shift Instructions

- Bit shifted out goes into the carry flag
 - » Zero bit is shifted in at the other end



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Shift Instructions

* count is an immediate value

shl AX,5

- * Specification of count greater than 31 is not allowed
 - » If a greater value is specified, only the least significant 5 bits are used
- * CL version is useful if shift count is known at run time
 - » E.g. when the shift count value is passed as a parameter in a procedure call
 - » Only the CL register can be used

→ Shift count value should be loaded into CL

mov CL, 5

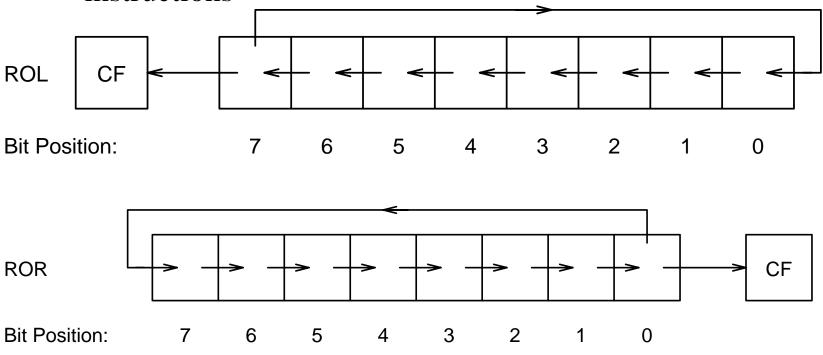
shl AX,CL

Rotate Instructions

- * Two types of ROTATE instructions
- Rotate without carry
 - » rol (ROtate Left)
 - » ror (ROtate Right)
- * Rotate with carry
 - » rcl (Rotate through Carry Left)
 - » rcr (Rotate through Carry Right)
- * Format of ROTATE instructions is similar to the SHIFT instructions
 - » Supports two versions
 - Immediate count value
 - Count value in CL register

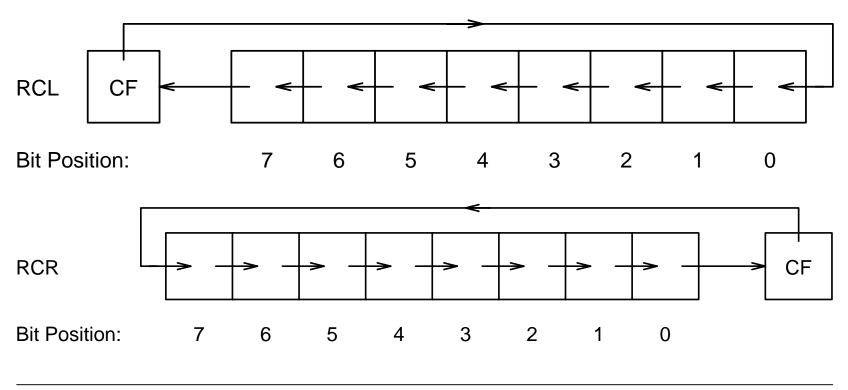
Rotate Instructions

* Bit shifted out goes into the carry flag as in SHIFT instructions



Rotate Instructions

* Bit shifted out goes into the carry flag as in SHIFT instructions



Defining Constants

- Assembler provides two directives:
 - » EQU directive
 - No reassignment
 - String constants can be defined
 - » = directive
 - Can be reassigned
 - No string constants
- Defining constants has two advantages:
 - * Improves program readability
 - * Helps in software maintenance
 - » Multiple occurrences can be changed from a single place
- Convention
 - » We use all upper-case letters for names of constants

Defining Constants

The EQU directive

• Syntax:

```
name EQU expression
```

- * Assigns the result of expression to name
- * The expression is evaluated at assembly time

Similar to #define in C

Examples

```
NUM_OF_ROWS EQU 50
NUM_OF_COLS EQU 10
ARRAY_SIZE EQU NUM_OF_ROWS * NUM_OF_COLS
```

* Can also be used to define string constants

```
JUMP EQU jmp
```

Defining Constants

The = directive

• Syntax:

```
name = expression
```

- * Similar to EQU directive
- * Two key differences:
 - » Redefinition is allowed

$$count = 0$$

is valid

» Cannot be used to define string constants or to redefine keywords or instruction mnemonics

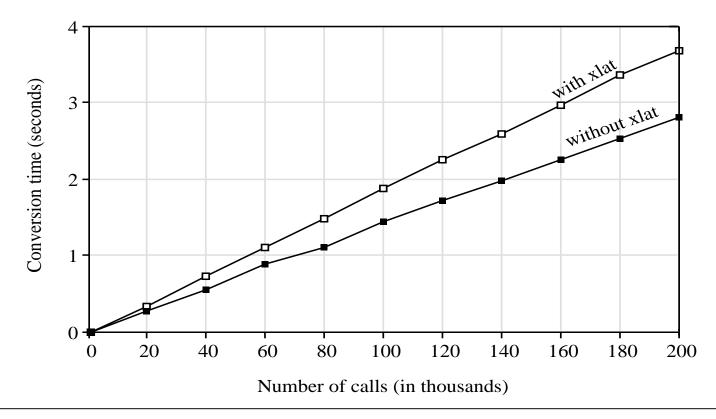
Example: JUMP = jmp is not allowed

Illustrative Examples

- Five examples are presented:
 - * Conversion of ASCII to binary representation (BINCHAR.ASM)
 - * Conversion of ASCII to hexadecimal by character manipulation (HEX1CHAR.ASM)
 - * Conversion of ASCII to hexadecimal using the XLAT instruction (HEX2CHAR.ASM)
 - * Conversion of lowercase letters to uppercase by character manipulation (TOUPPER.ASM)
 - * Sum of individual digits of a number (ADDIGITS.ASM)

Performance: When to Use XLAT

- Lowercase to uppercase conversion
 - XLAT is bad for this application



Performance: When to Use XLAT (cont'd)

Hex conversion

XLAT is better for this application

